



Performance Comparison of L-UPQC and R-UPQC with FUZZY logic Controller for Power Quality Improvement

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Abstract : In the modern power system, the usage of power electronic loads was statically high and it behaves as non-linear load. This load causes the serious voltage distortion and power quality issues on the transmission and distribution system by injecting the harmonics. Usually active power filters are used to regulate this problem. Unified power quality conditioner is the combination of series and shunt active power filters. It not only eliminates the harmonics, also it treats all type of voltage and current fluxuations and compensate the reactive power in distribution system. In this paper new topology of unified power quality conditioner with different control strategy was introduced to rectify the power quality issues and increase the strength of power quality. UPQC concern feedback system with FUZZY logic controllers was used to improve the performance of UPQC and compare the results using MAT LAB/SIMULINK.

Index Terms : L-UPQC, R-UPQC, Active Power Filters, Power Quality.

I. Introduction

An electric power system is a network of electrical components deployed to supply, transfer, store, and use electric power. An example of an electric power system is the grid that provides power to an extended area. An electrical grid power system can be broadly divided into the generators that supply the power, the transmission system that carries the power from the generating centres to the load centres, and the distribution system that feeds the power to nearby homes and industries[1]. Compared to generation and transmission we have huge power quality issues on distribution system. The impacts of power quality problems are voltage surges/spikes, voltage dips, under voltage, high-voltage spikes, frequency variation, power sag, electrical line noise, brownouts, blackouts, very short interruptions, long interruptions, voltage swell, and harmonic distortion.[2].

Now a day we frequently using variety of sensitive loads such as computer, led television, home automation, etc. Due to poor power quality such equipment may failure or less life span. To diagnose this

problem and also to improve the power quality we have only solution, called Active Power Filters. The Active Power Filters (APF) are the most promising solution to reduce the power quality issues and made it possible to mitigate the PQ problems effectively. The APF is split into series active power filter (se-APF) and shunt active power filter (sh-APF). The series active power filter is operated to diagnose the source side problems. Likewise, shunt active power filter is operated to diagnose the load side problems[3].

UPQC is one of APF families which consists of both series and shunt active power filters to achieve the extreme compensation for rapid PQ problems. The UPQC is a hybrid compensation device which tolerates both voltage and current related problems. The source side problems are referred as voltage related problems and it is compensated by series active filter. Typically, the load side problems are current related problems and it is compensated by shunt active power filter. The both series active power filter and shunt active power filter are coupled with dc capacitor for dc link.[3] The series APF is connected via an injection transformer with the ac line. The isolation of voltage based distortion is done by the series APF and the isolation of current based problems is done by the shunt APF

II. Problem Formation

The mathematical formulation of two voltage sag indices (ξ and ζ 1,2) is introduced in addition because the results of the investigation towards their accuracy institution. The Mathematical equations describing the event of a Combined Voltage Index (CVI) are bestowed in addition because the results obtained by the verification method. The index supervises the ability of a system, through characterizing voltage sags [4]. The voltage sags square measure caused by a rise in reactive demand owing to induction motor beginning.

A feeder can be modelled by an equivalent two-port network, as shown in Figure 1. The sending end voltage and current of the system can be represented by equations (1) and (2).

$$U_s \angle \delta_s = AU_r \angle \delta_r + BI_r \quad 1$$

$$I_s = CU_r \angle \delta_r + DI_r \quad 2$$

Where I_s the sending end current, U_s is the sending end voltage, U_r the receiving end voltage, I_r the receiving end current, δ_r the receiving end voltage angle, δ_s the sending end voltage angle, and ABCD are the two port network constants.

For a short length line, equivalent to distribution network, the two port network parameters are often approximated as: $A=D=1$, $B= Z \angle \theta$, $C=0$. Where Z is that the line resistivity vector magnitude, and θ the line resistivity vector angle.

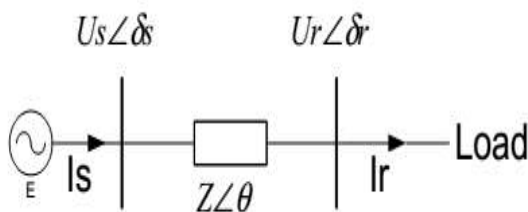


Fig. 1. The equivalent two port network model.

The line power flow, for the active power at the sending and receiving end of the line, can be described by (3) and (4).

$$P_r = \frac{U_s U_r}{Z} \cos(\theta + \delta_r - \delta_s) - \frac{U_r^2}{Z} \cos(\theta) \quad 3$$

$$P_s = \frac{U_s^2}{Z} \cos(\theta) - \frac{U_s U_r}{Z} \cos(\theta + \delta_s - \delta_r) \quad 4$$

A. For multi-channel three phase measurement

The voltage sag starts once the RMS voltage URMS (1/2), drops below the threshold in a minimum of one in all the channels, and ends once the RMS voltage recovers on top of the threshold in all channels. The preserved voltage for a multi-channel activity is that the lowest RMS voltage in any of the channels. many strategies are investigated resulting in one index for every event. Though this ends up in higher loss of data, it simplifies the comparison of events, sites and systems. [4] the final downside of any single-index technique is that the result not directly relates to equipment behavior. Single indices are shortly represented below.

Voltage Loss: The loss of voltage “ L_v ” is defined as the integral of the voltage drop during the sag event.

$$L_v = \int \{1 - V(t)\} dt \quad 5$$

Energy Loss: The loss of energy “ LE ” is defined as the integral of the drop in energy during the event:

$$L_E = \int \{1 - V(t)^2\} dt \quad 6$$

The energy of voltage sag (EVs) as:

$$E_{Vs} = (1 - V_{Pu})^2 \times t \quad 7$$

Where ‘ t ’ is the sag duration.

The concept of ‘energy loss during a sag event’ was found, in such how that the lost energy for events on the Computer Business Equipment Manufacturers Association (CBEMA) curve is constant for three-phase measurements. The lost energy is another for the three phases:

$$W_a = \left\{1 - \frac{V_a}{V_{a\text{nominal}}}\right\}^{3.14} \times t \quad 8$$

To include non-rectangular events an integral expression may again be utilized. The event severity index (S_e) is taken from the event magnitude in Pu and the event duration. Also needed for the method is the definition of a reference Curve.

$$S_e = \frac{1-V}{1-V_{ref}(d)} \quad 9$$

Where $V_{ref}(d)$ is the event magnitude value of the reference curve for the same event duration. This method is observed by the use of the CBEMA and Information Technology Industry Council (ITIC) as reference curves. However, the method is equally applicable with other curves also.

III. UPQC State of Art

Generally, the construction of unified power quality conditioner is different from all other facts devices. It consists of both series active power filter and shunt active power filter. UPQC employs two voltage source inverters that are connected to common DC energy storage capacitor [8] - [19]. One of these two VSIs is connected in series with ac line while the other is connected in shunt with the same line[5].It is installed in the power transmission system to execute both series and shunt compensation at the same time.

Figure 2 illustrates the schematic structure of Unified Power Quality Conditioner. The series APF is installed to compensate the source side issues like sag, swell, interruption, etc. And the shunt APF is employed to tackle the load side issues like harmonic and power factor.

$$i_{sh}(\omega t) = \hat{i}_s(\omega t) - i_l(\omega t) \quad 10$$

$$v_{se}(\omega t) = v_l(\omega t) - v_s(\omega t) \quad 11$$

The shunt inverter should inject a current as governed by above equation (6) to eliminate the harmonics generated by the non-linear loads in the distribution system. Also, the basic operation of a series inverter can be represented in equation (7).

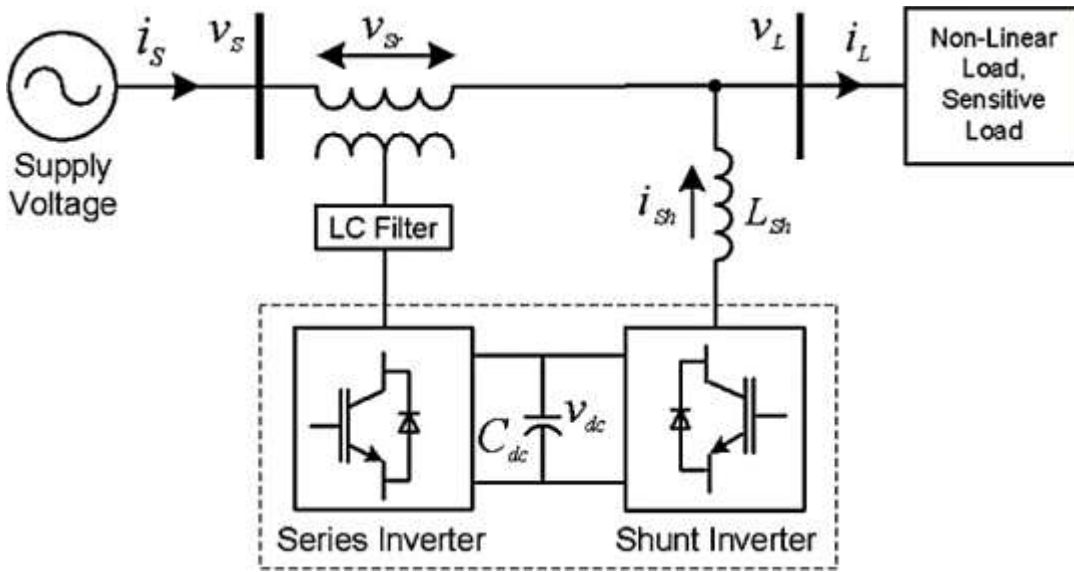
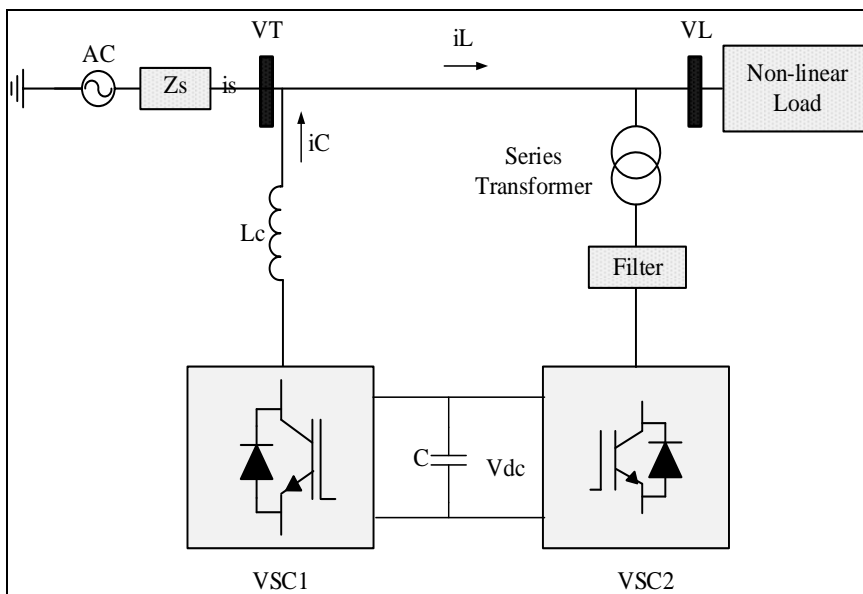


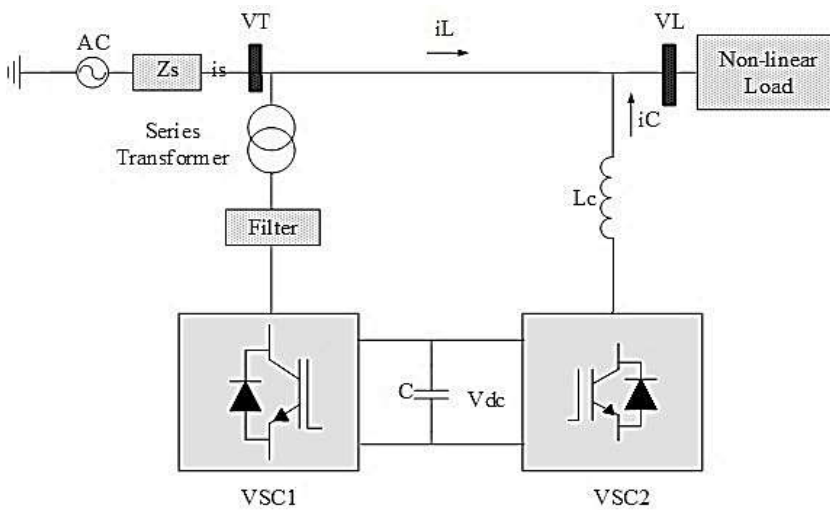
Fig. 2. Structure of UPQC

A. UPQC Configuration

Both structures of UPQC, R-UPQC and L-UPQC connected to a single feeder distribution system which supply a sensitive critical non-linear load are shown in Fig. 3. The shunt compensator, VSC 1 which operates as a controlled current source is used to compensate load current harmonics, to provide the reactive power required by the load and to support the real power required by the series compensators to maintain the dc link capacitor voltage at a desired level.[6] The series compensator, VSC2 is used as controlled voltage source to protect the sensitive/nonlinear load against input supply voltage imperfections. Some other UPQC configurations are shown in reference [21]-[25]



(i)



(ii)
Figure 3: Structure UPQC Configuration (i) R-UPQC (ii) L-UPQC

In Fig. 1, v_s , v_T , v_L , v_C are source, terminal or point of coupling, load, and compensation voltages, respectively, and i_s , i_L , i_C are supply, load and compensation currents, respectively. In both UPQC topologies the ac side of shunt VSC1 is connected to the distribution system through a commutation reactor which denote by LC where the ac side of the series, VSC2 is connected to the distribution system through a single phase transformer, commutation reactor and small high-pass filter which used to prevent the flow of switching harmonics into the distribution systems.

IV. Fuzzy Logic Controller

Vagueness is the meaning of FUZZY. It is used to solving the uncertainty in the problem. It uses the interval between 0 and 1 for human reasoning. The FUZZY operation works by two stages and are Fuzzification and Defuzzification. The process of converting the crisp input to a fuzzy value is called as Fuzzification. The output of the fuzzy is developed with the rules. The basic operation of the FLC is constructed from fuzzy control rules utilizing the value of fuzzy sets in general for the error and change of error and control action. The results are combined to provide a crisp output controlling the output variable and this process is called as defuzzification. The sign of the error signal and the output from linguistic codes given in the table.

Table 1: Fuzzy Logic Truth Table

| CHANGE IN ERROR | ERROR | | | | | | | |
|-----------------|-------|----|----|----|----|----|----|----|
| | | NB | NM | NS | Z | PS | PM | PB |
| | NB | NB | NB | NB | NB | NM | NS | Z |
| | NM | NB | NB | NB | NM | NS | Z | PS |
| | NS | NB | NB | NM | NS | Z | PS | PM |
| | Z | NB | NM | NS | Z | PS | PM | PB |
| | PS | NM | NS | Z | PS | PM | PB | PB |
| | PM | NS | Z | PS | PM | PB | PB | PB |
| | PB | Z | PS | PM | PB | PB | PB | PB |

V. Simulation Results Comparison

In order to verify the performance of both UPQC topologies (i.e.) R-UPQC and L-UPQC based on FUZZY LOGIC controller, comprehensive simulations studies have been carried out with the help of power system simulation package MATLAB/Simulink. Supply voltage, 400 V, 50 Hz for a single feeder distribution system as in both Fig. 4 & 5 is employed.

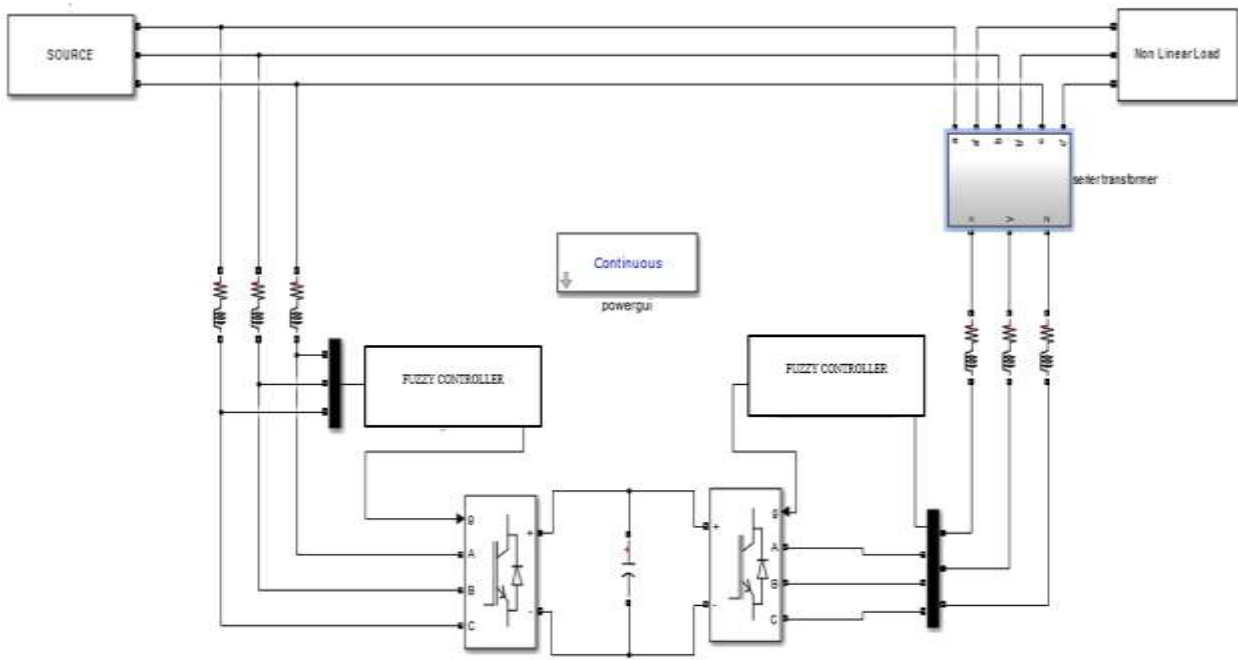


Fig.5. MATLAB/Simulink model for single unit infinite bus system with R-UPQC

A sensitive critical non-linear load assumed as a parallel combination of balanced three-phase R-L load ($R=25$ Ohms, $L = 15.7$ mH) and a three-phase diode bridge rectifier followed by R-L load on the dc side ($R = 52$ Ohms, $L = 21$ mH) which draws harmonic currents is connected to the feeder.

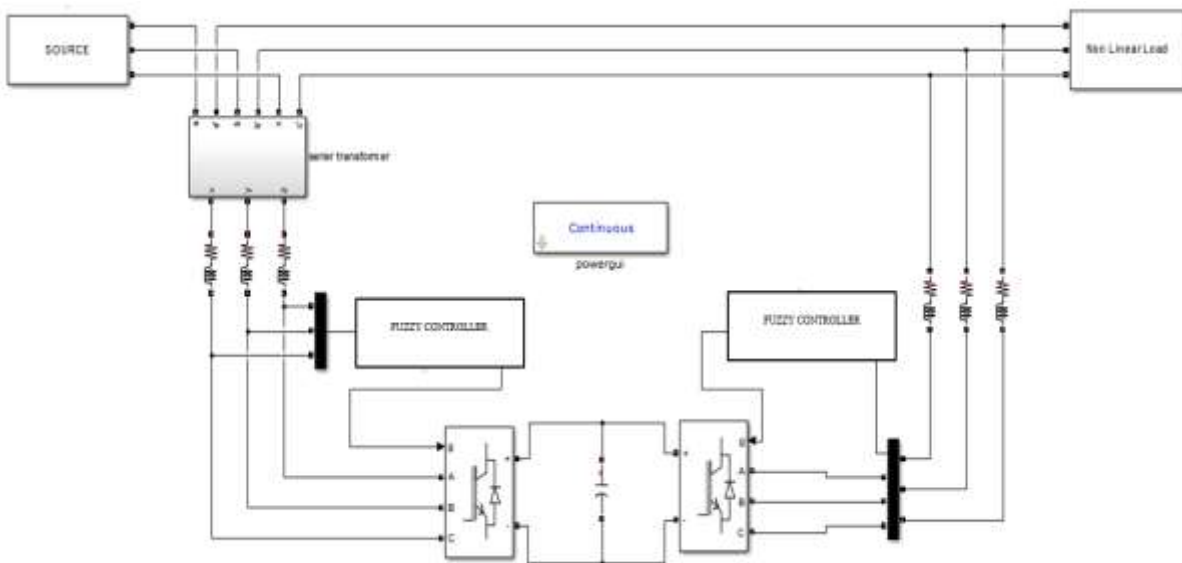


Fig. 6. MATLAB/Simulink model for single unit infinite bus system with L-UPQC

Figure 7 & 8 shows the output results of both R-UPQC and L-UPQC Here we manually trigger the non-linear load at the time of 0.4s. Later we manually operate the active power filters at the time of 0.6s. This process was experimented for quick understanding of UPQC characteristics.

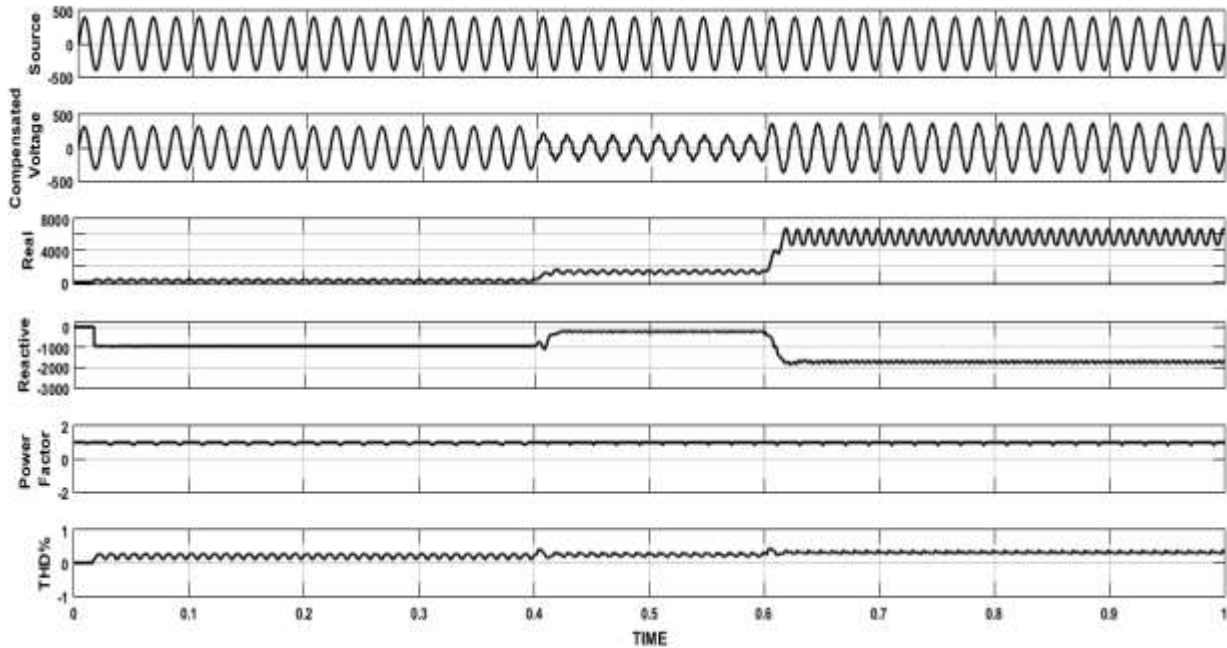


Fig. 7. Simulation Results for R-UPQC

The simulation result of Total Harmonic Distortion (THD) of load and source currents before compensation is observed to be 24.4 %. After compensation the source current THD is significantly reduced to 0.12 % by R-UPQC and to 0.21 % by L-UPQC. It is shown that both UPQC topologies have appreciable effect as current harmonic filters which prevented the load current harmonics from flowing into the source. Table 2 illustrates the results comparison of L-UPQC & R-UPQC.

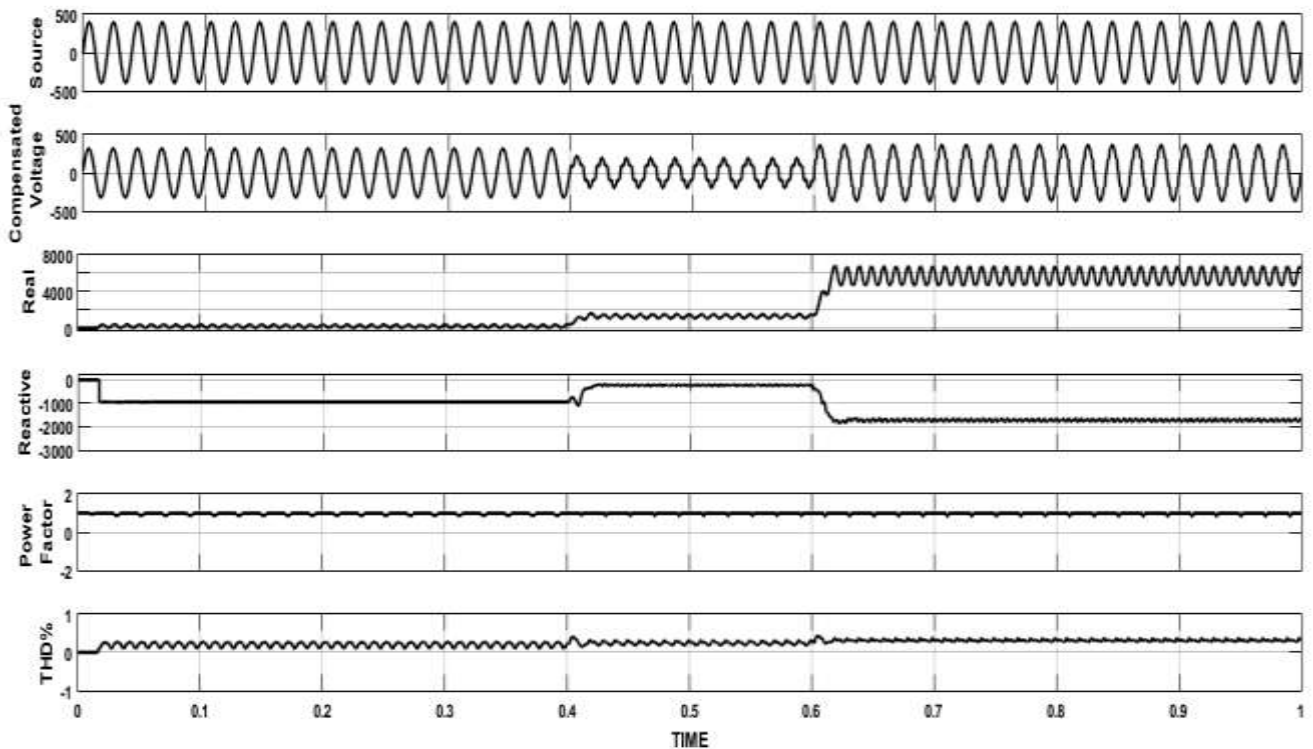


Fig. 8. Simulation Results for L-UPQC

Table 2. Comparison of left and right UPQC

| S.No | Factors | L-UPQC | R-UPQC |
|------|-----------------|--------|--------|
| 1 | Input Voltage | 400V | 400V |
| 2 | Non-Linear Load | RL | RL |
| 3 | THD | 0.21 % | 0.12 % |
| 4 | Power Factor | 0.975 | 0.9989 |

VI. Future Scope

In this paper new topology of UPQC were simulated with FUZZY LOGIC controller and its results are shown. Future the FUZZY LOGIC controller may be replaced by any newer control strategy to get better achieve results.

VII. Conclusion

In this work both UPQC topology was deeply studied and the compensation performance of UPQC is established by the MATLAB/Simulation results on a single feeder distribution system. It is observed that the L-UPQC, R-UPQC topology only has the capability of operating in zero power absorption/injection modes. It is noticed that R-UPQC gives better compensation than the L-UPQC by reducing the THD of load voltage and source current. However, the UPQC topologies provides better compensation strength to mitigate voltage harmonic and minimize oscillating reactive power component based on FUZZY LOGIC controller.

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